

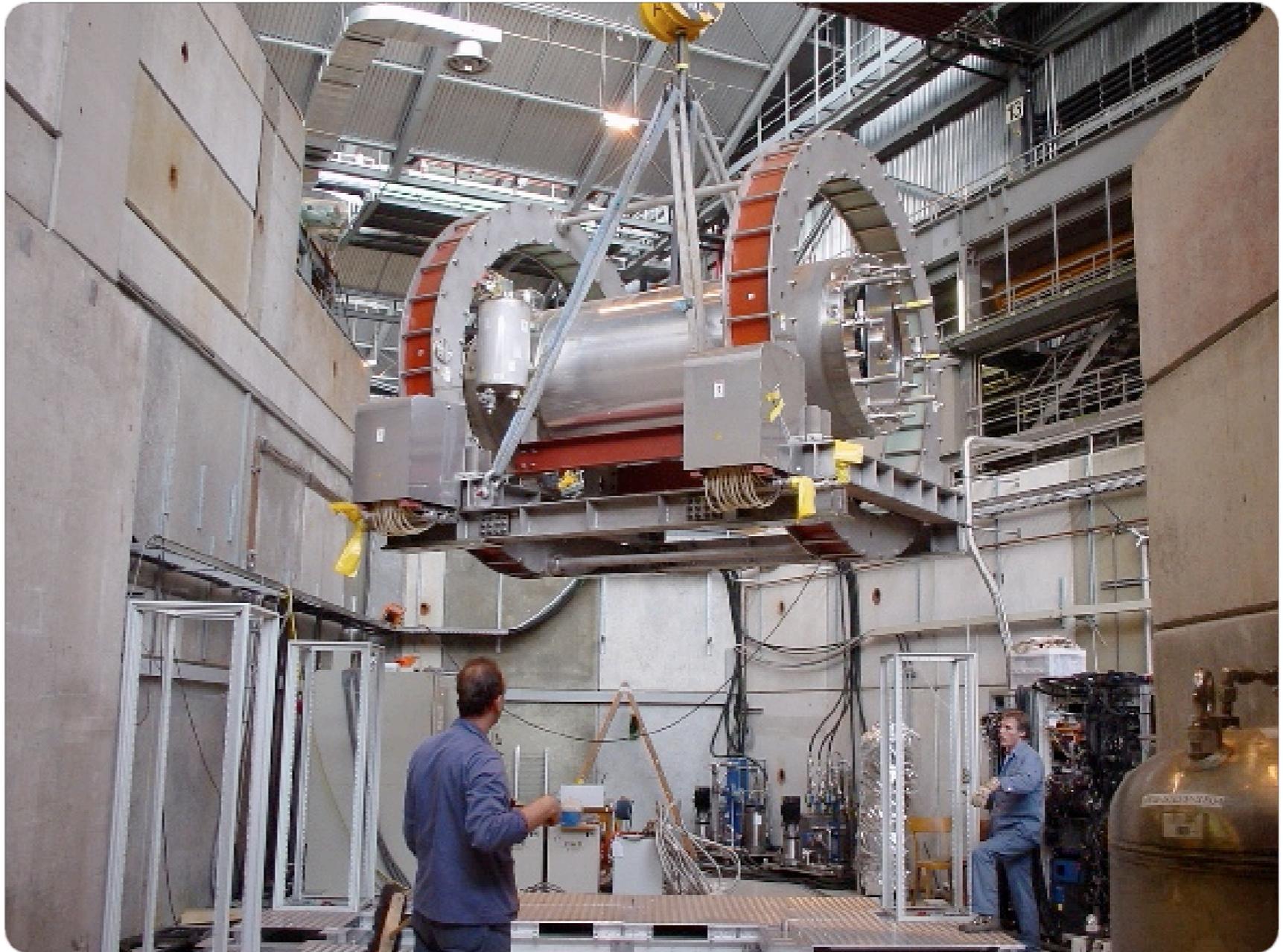
COBRA Magnet

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MEG Review Meeting, Jul. 19th, 2005

Outline

- Field Measurement
- Field Monitor
- Fringe Field Problem
- Area Related



Field Measurement

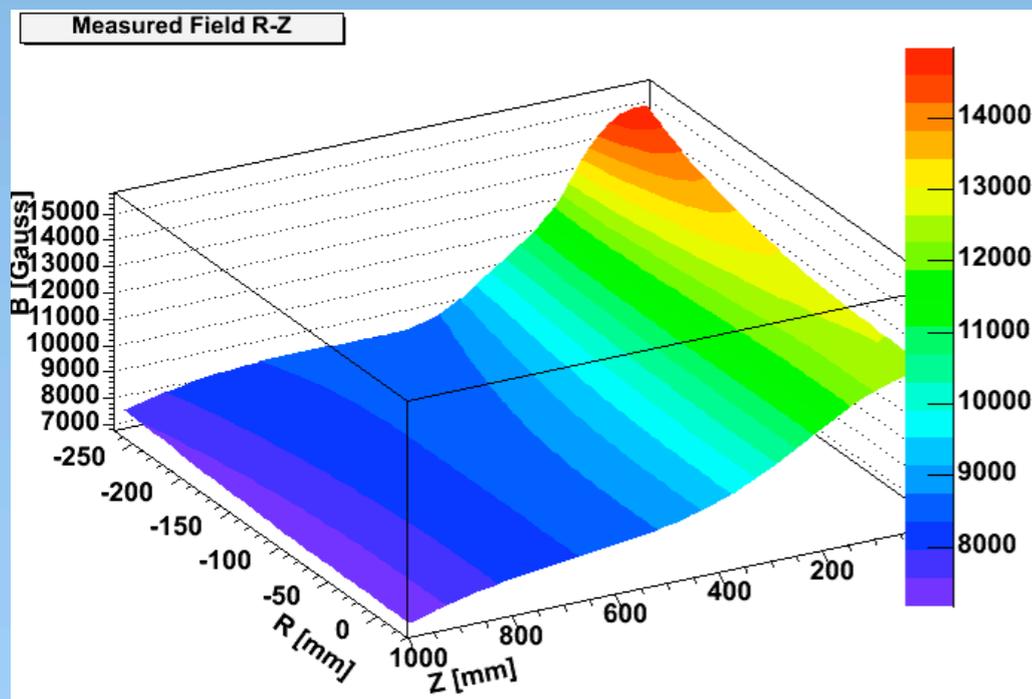
Field Measurement

- ⊙ Problem in Z-motion of the mapping machine solved.
- ⊙ Positioning accuracy for Z-motion $< 0.8\text{mm}$
- ⊙ Test measurement of the COBRA field with the mapping machine was carried out at the end of March.
- ⊙ Several measurements for limited volume.
 - ⊙ 3D scan around magnet center (6174 points)
 - ⊙ 2D scan (R-Z) on half R-Z plane (3223 points)
 - ⊙ 2D scan (R- ϕ) around magnet center (591 points)
- ⊙ Mapping machine and control software worked well.
- ⊙ Investigation of COBRA field monitor
 - ⊙ NMR or Hall probe?

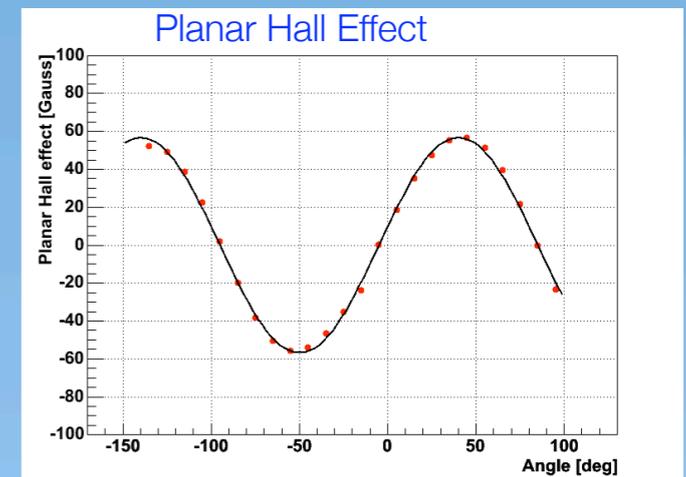
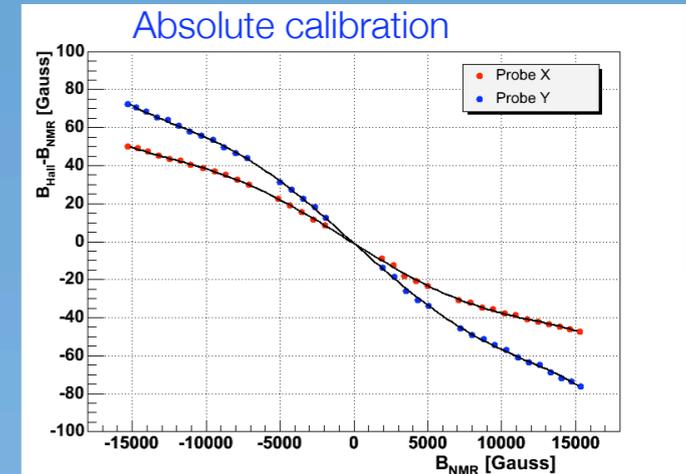
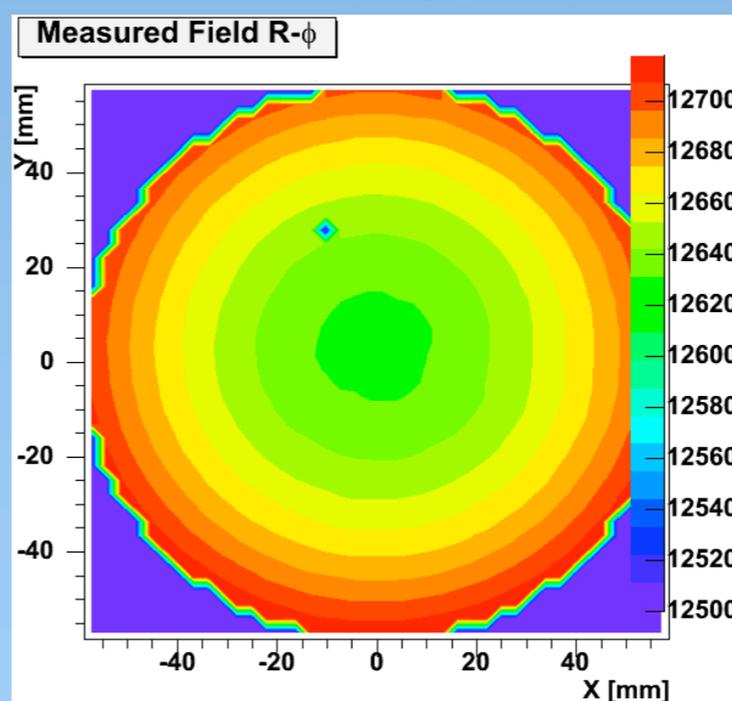
Analysis

- Analysis should include
 - Absolute calibration of the Hall probes
 - Planar Hall effect
 - Distance among the three probes (not included yet)
- Analysis is still going on.

Measured Field (R-Z plane)

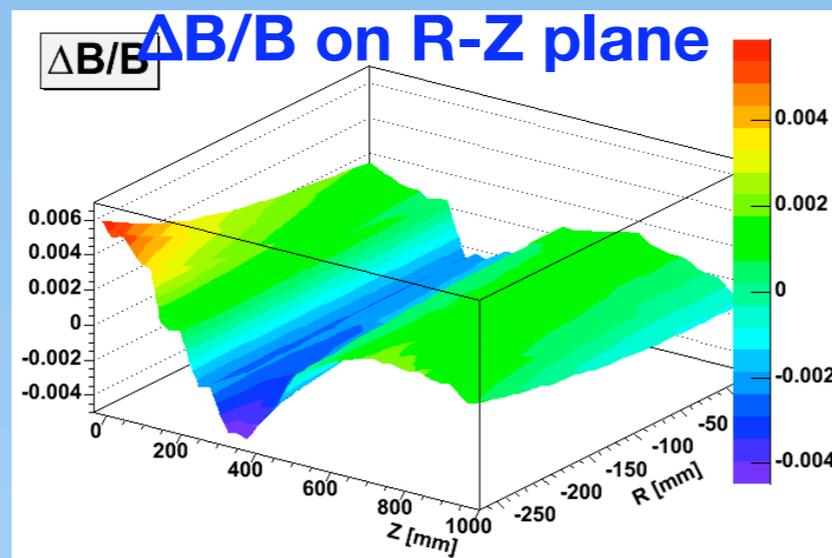


Measured Field (R- ϕ plane)



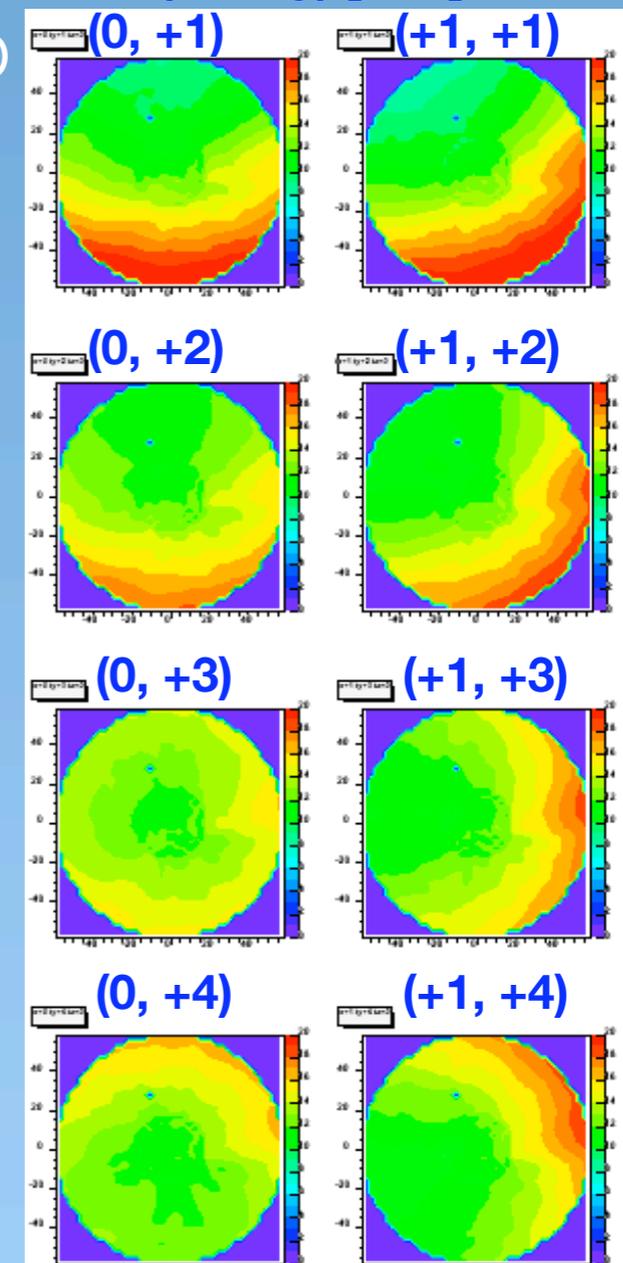
Comparison with Calculation

- Measured field is compared with calculated field.
- Small discrepancy within $\pm 0.5\%$ is observed .
- Coil center position seems to be shifted relative to cryostat center.
- Estimated shift (preliminary)
 - x~0mm, y~+3mm (upward), z~-3mm (upstream)
- Larger shift than expected. why?
- Effect on the detector performance?
- Quick MC study shows the effect looks negligible.



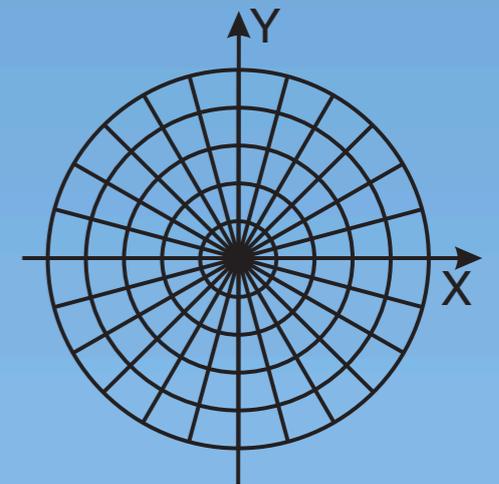
ΔB on R-Phi plane

$(\Delta x, \Delta y)$ [mm]



Mesh Size in Field Measurement

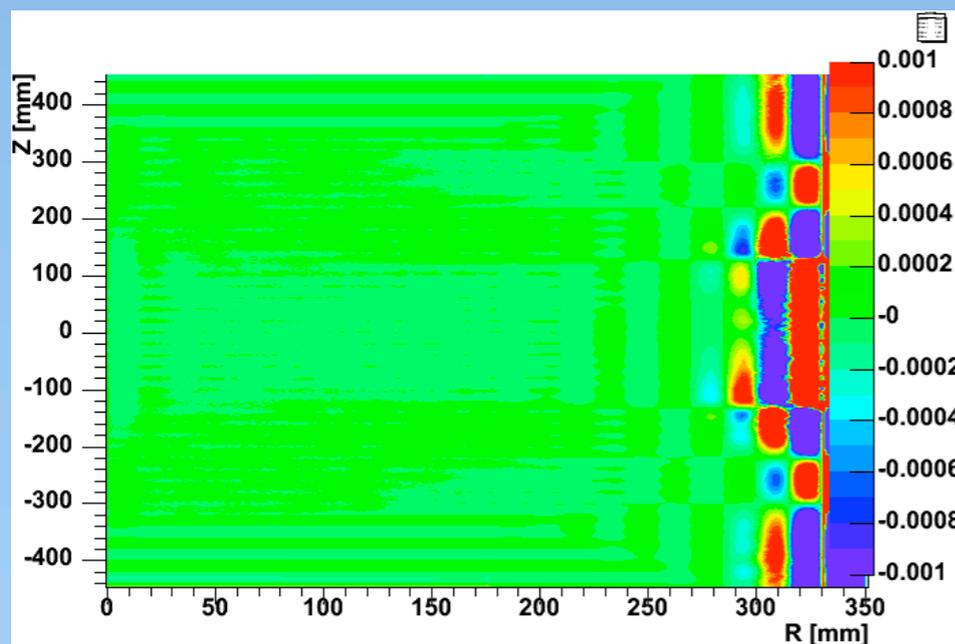
- ⊙ It is easier to measure the field at the grid points in the cylindrical polar coordinate system (r, z, ϕ) because the motion of the mapping machine is cylindrical.
- ⊙ Potential problem with the cylindrical grid.
 - ⊙ Coarser mesh in ϕ -direction at larger radius
 - ⊙ $\Delta L \sim 5\text{cm}$ at $R = 30\text{cm}$ if $\Delta\phi \sim 10$ deg
 - ⊙ It shouldn't be a big problem because the COBRA field is expected to be axi-symmetric
- ⊙ What is the optimum mesh size in the final measurement?
 - ⊙ Time slot for field measurement ~ 1 month
 - ⊙ How to interpolate between measuring points?



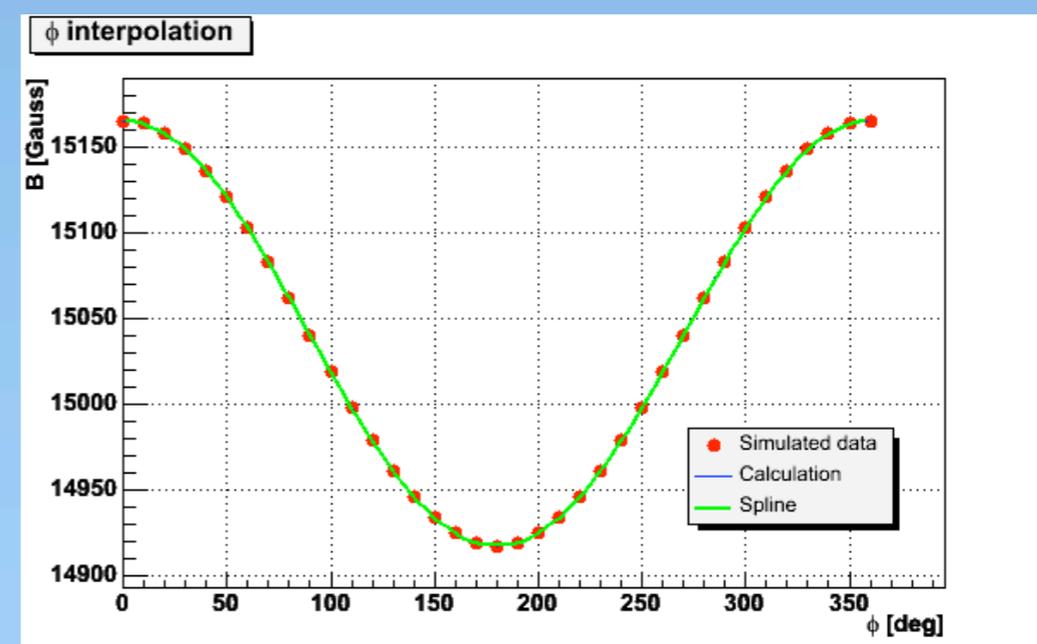
Mesh Size in Field Measurement

- ⊙ Interpolation between measuring points were tested using calculated field map.
- ⊙ Cubic spline interpolation
- ⊙ Interpolation error is negligible for $\Delta Z < 2\text{cm}$, $\Delta R < 2\text{cm}$, $\Delta\phi < 30\text{ deg}$
- ⊙ How many days we need?
 - ⊙ 10 to 20 full days with $\Delta Z = 1\text{-}2\text{cm}$, $\Delta R = 1\text{-}2\text{cm}$, $\Delta\phi = 10\text{-}20\text{deg}$
 - ⊙ One month in total including calibration and other preparation.

$\Delta B/B$ in the simulated interpolation on R-Z plane assuming $\Delta Z = 2\text{cm}$, $\Delta R = 1.5\text{cm}$

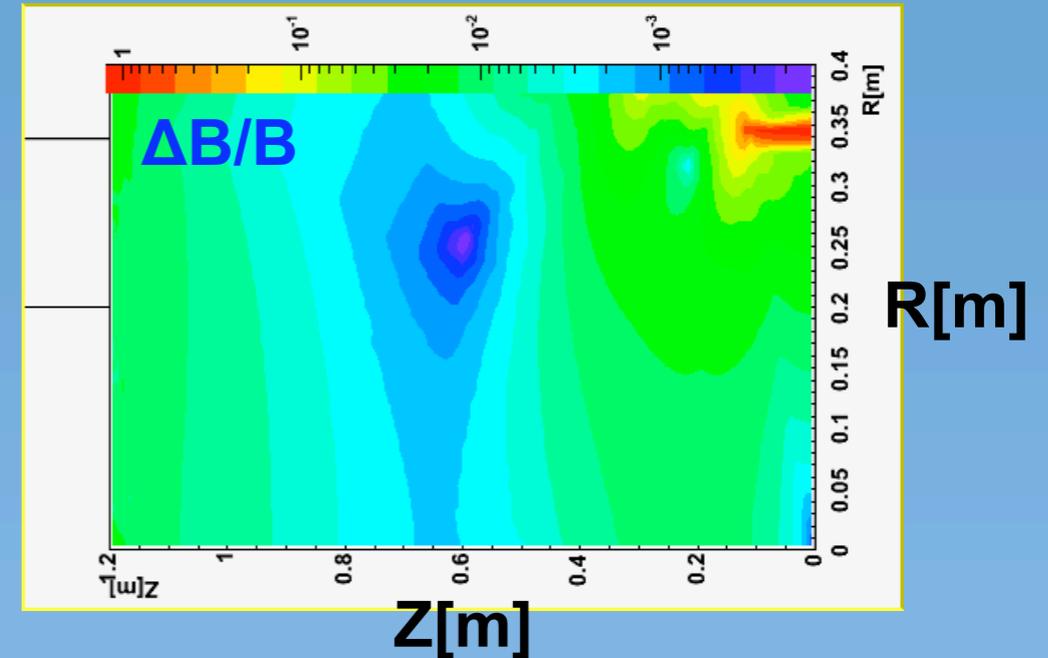


Simulated interpolation in ϕ -direction assuming 5mm shift of mapping machine center and $\Delta\phi = 10\text{deg}$



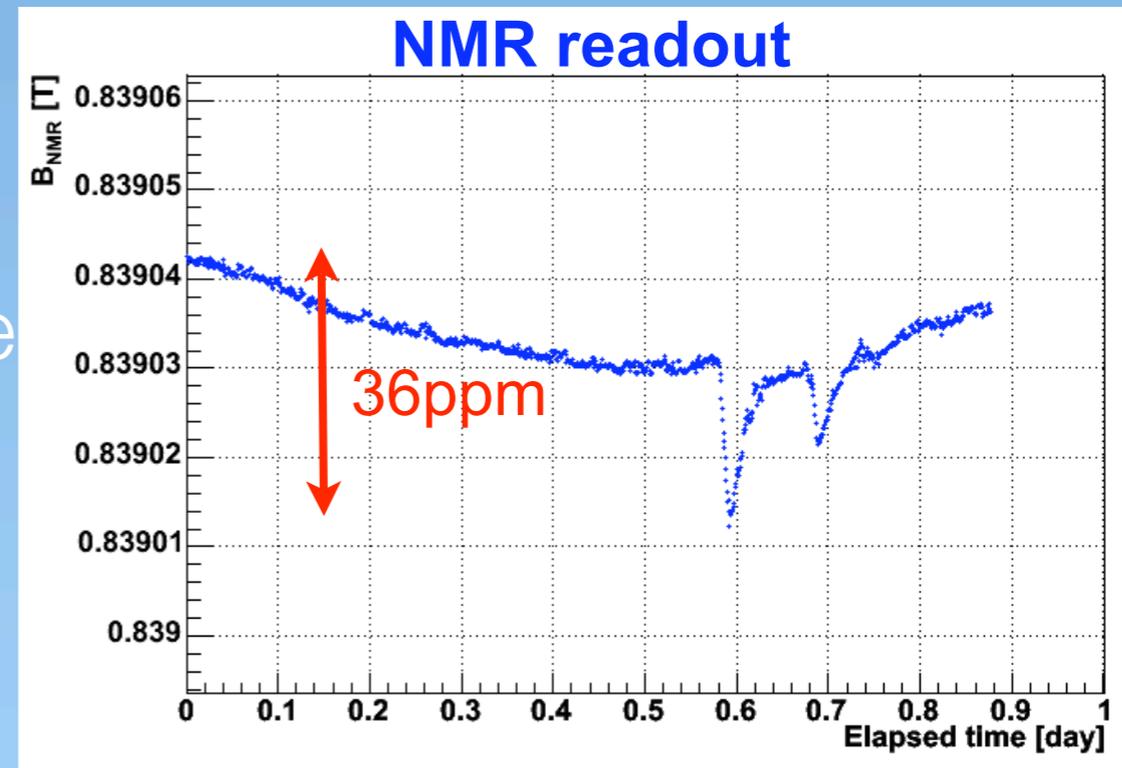
How to Monitor COBRA Field?

- How to monitor COBRA field stability
 - Current monitoring
 - Field monitoring
 - NMR
 - Hall probe
- NMR and Hall probe were tested.



NMR

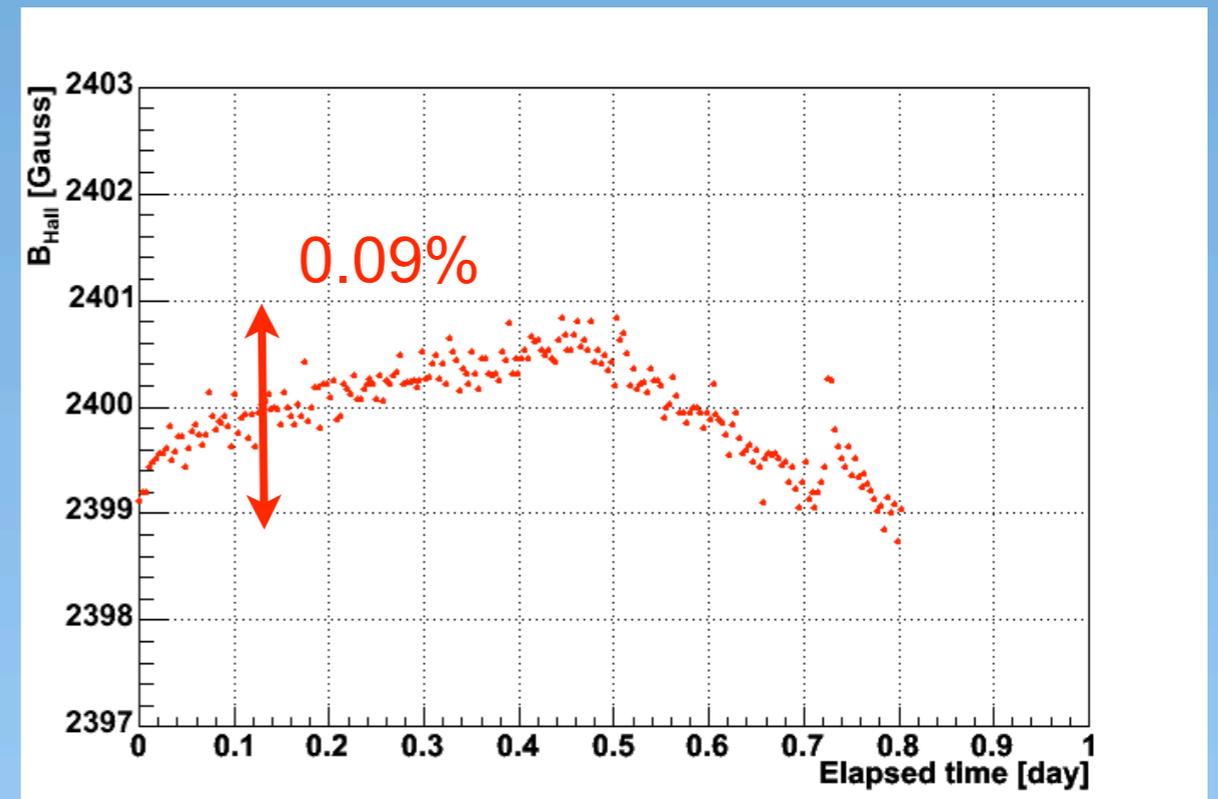
- Only one possible location for NMR inside COBRA.
- NMR was not locked anywhere else actually. (both inside and outside)
- Daily calibration?
- It was found that COBRA field is pretty stable.



How to Monitor COBRA Field?

Hall probe

- ⊙ Temperature coefficient
- ⊙ Need careful calibration
- ⊙ Stability was measured at the end of the COBRA cryostat.
- ⊙ Stability $\sim 0.09\%$ for one day
- ⊙ Not so bad
- ⊙ This might be improved because of the temperature stabilization inside the detector hut.

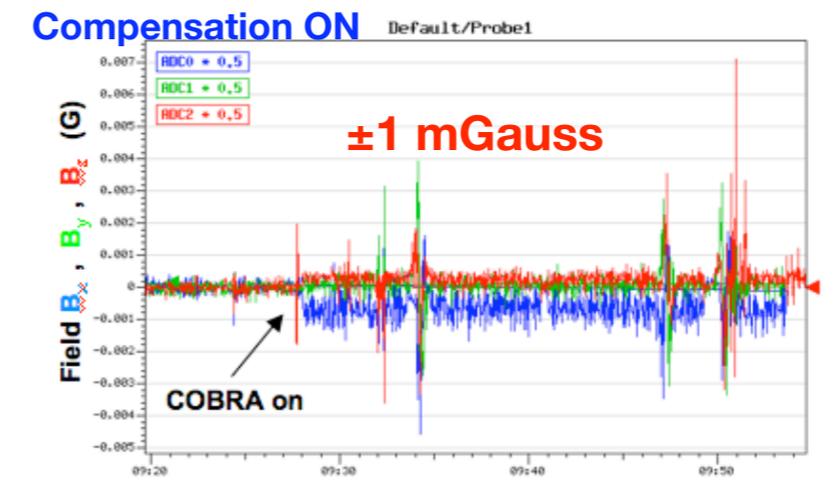
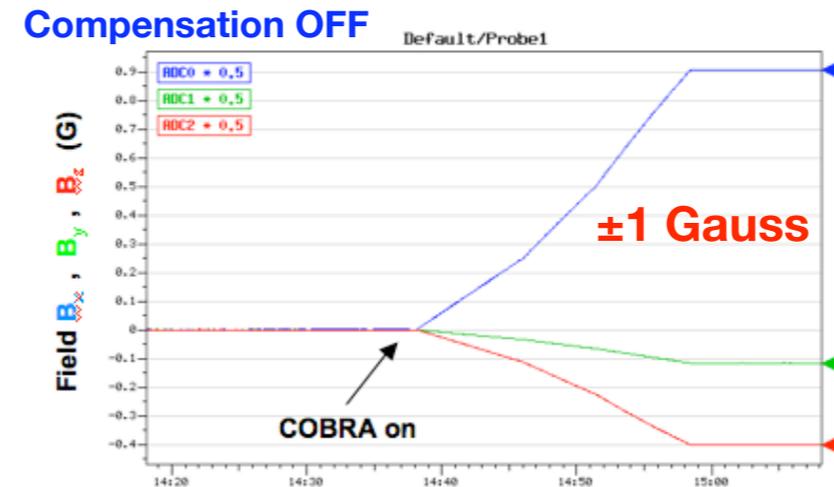
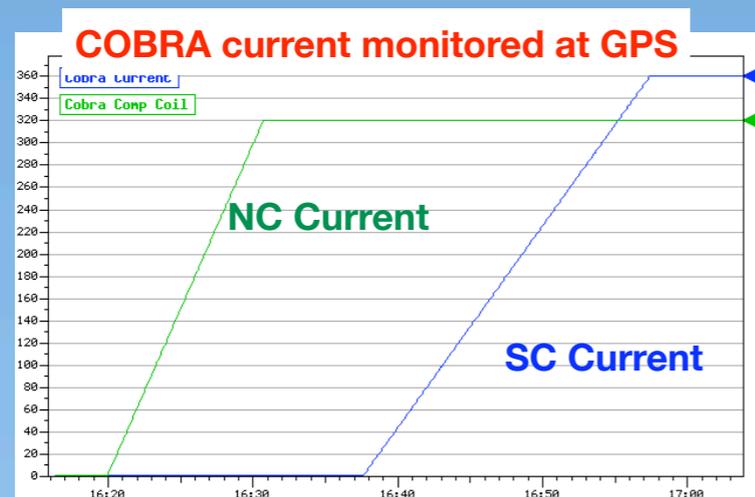


Fringe Field Problem

Fringe Field Problem

- ◎ First success of the excitation of the COBRA magnet with the accelerator ON!! (Jul. 20th and 21st).
- ◎ There seemed no influence on neighboring beam channels and primary beam line. (Nobody complained at least.)
- ◎ Fringe field problems are already solved except for $\pi E3$.
- ◎ Effect on the detector in $\pi E3$ was measured in Jun.
- ◎ The fringe field ($\sim 4G$) is close to the upper limit of the requirement.
- ◎ Simple shielding is sufficient.
 - ◎ Iron plates on one side wall and floor
- ◎ How to cope with the other experiments in the $\pi E5$?

COBRA Status Broadcast

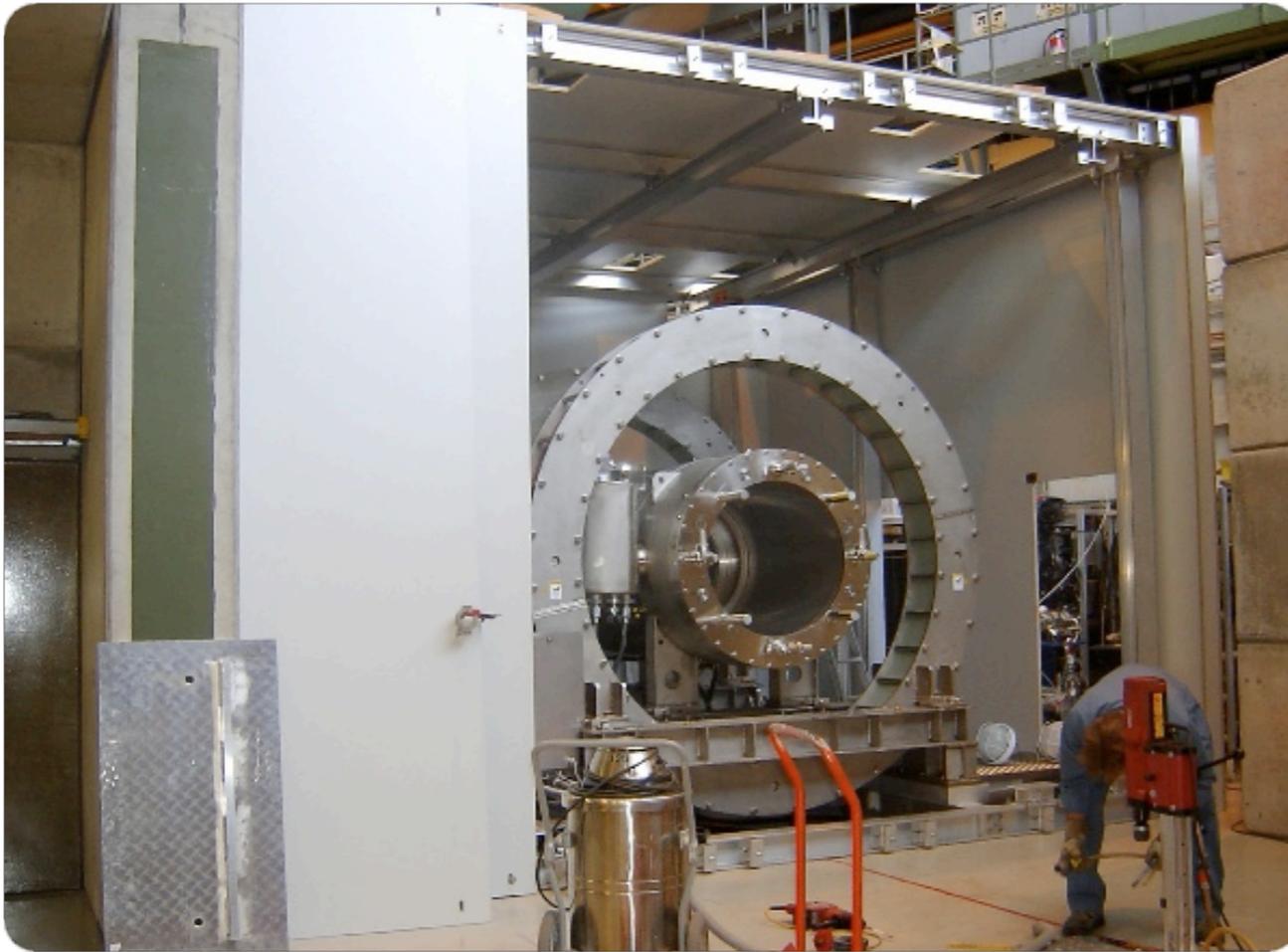


Pictures courtesy of H.Luetkens of μ SR group

- ⊙ The COBRA magnet status is now broadcasted over the network to the neighbors.
- ⊙ MSCB module developed by S. Ritt and R. Schmidt.
- ⊙ The active compensation system of the GPS in π M3 already succeed to use the status info. (thanks to H.Luetkens of μ SR group)

Area Related

Detector Platform and Hut



- ◎ Detector platform and hut were installed.
- ◎ Things to be done
 - ◎ Cabling
 - ◎ Lamp inside hut
 - ◎ Air conditioning
 - ◎ Oxygen monitor
 - ◎ Monitoring camera

Another Platform



- ◎ The second platform was installed at the end of the zone.
- ◎ Magnet controller, cooling water system, compressors and air conditioning system for the detector hut will be placed.
- ◎ Made of steel
 - ◎ The effect on the COBRA field is negligibly small.