物理ラン開始へ向けた MEG II実験検出器のアラインメント

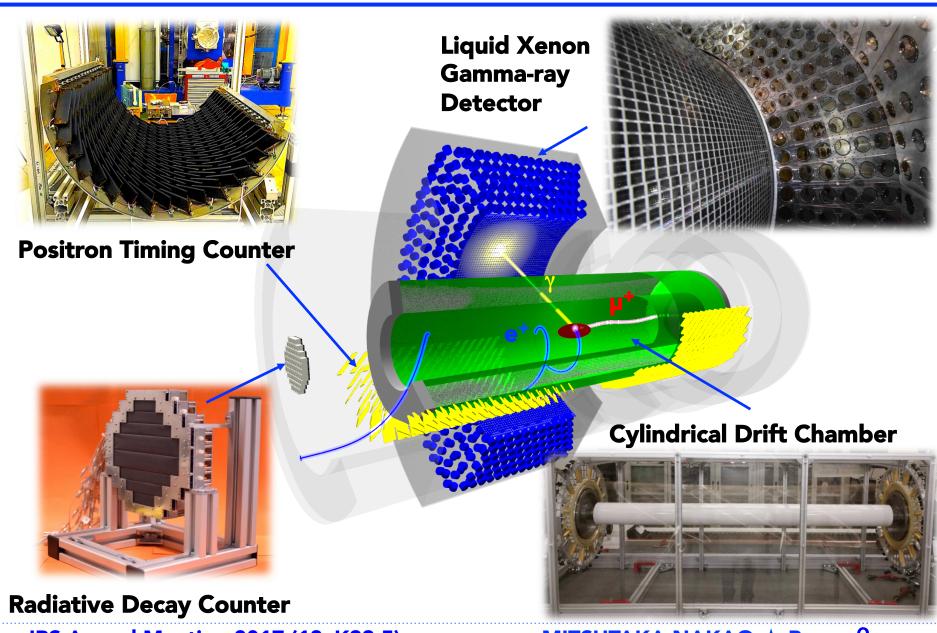
MEG II Detector Alignment Towards Physics Run

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On behalf of MEG II Collaboration



MEG II Detector

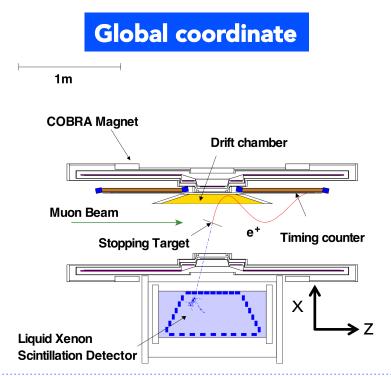


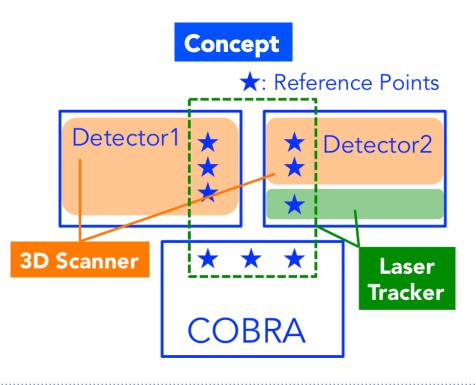
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Detector Alignment in MEG II

- The goal is to know the position of detectors in global coordinate with a high accuracy.
- 3D Scanner will be used for measurements within a detector(local position).
- Laser Tracker will be used for making connections among detectors(global position).
- Reference points are measured by both methods.





3D Survey

3D Scanner (FARO)





Laser Tracker (Leica)



- Composed of laser head and corner cube.
- Laser emitted from laser head is reflected at corner cube.





Xcited from FARO website, but we do not use FARO's one!

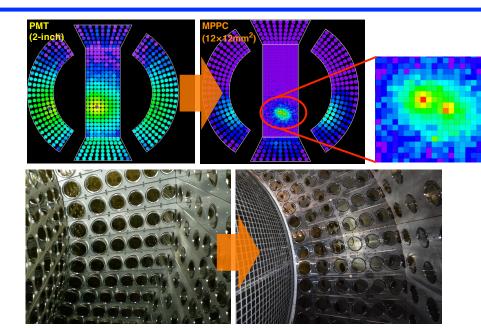
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MEG II LXe Detector

LXe Upgrade Better resolution for γ

- Replace PMTs on inner face with MPPCs.
- Modified PMT layout at lateral face.
- Wider inner face.
- Better uniformity of photon collection (better ΔE).
- Higher granularity of scintillation readout (better Δx).





Hamamatsu S10943-4372

15_{mm}

side view

2.5mm

- 50 µm pitch pixel
- $6 \times 6 \text{ mm}^2 \times 4 \text{ chips}$
- crosstalk and afterpulse suppression
- quartz window for protection
- ceramic package

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LXe Detector Alignment

Requirement

- More precise alignment is required for LXe since resolutions will be significantly improved.
- Target precision: ~500 μm

Our Plan

- Global position of LXe in experimental area(πΕ5).
 - → global coordinate.
 - laser tracker + corner cube.
- Local position of photo-sensor in LXe.
 - 3D scanner for MPPCs
 - Laser tracker for PMTs

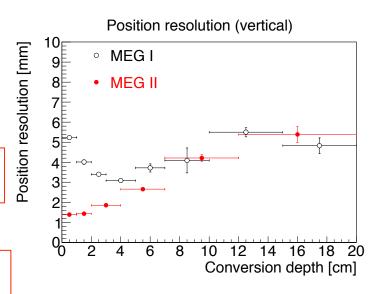
during sensor installation @ room temperature

- Possible displacement/deformation.
 - x-ray survey
 - potentiometer
 - cosmic ray

after installation @ LXe temperature(165 K)

Detector performance for signal γ-ray

	MEG (measured)	MEG II (simulated)
Efficiency	65%	70%
Position	~ 5 mm	~ 2.5 mm
Energy	~ 2%	0.7 - 1.5%
Timing	67 ps	40 - 60 ps



Measurements

PMT (Laser Tracker)

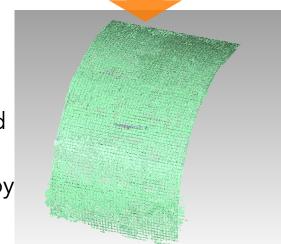
MPPC (3D Scanner)



corner cube

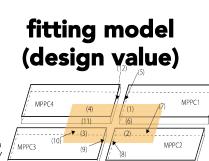


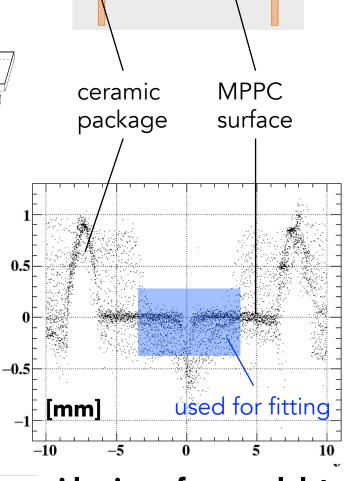
- y:X:Z
- We performed 3D measurements using laser tracker and 3D scanner.
- PMT holders were measured by laser tracker.
- All MPPCs were measured by 3D scanner.



Analysis of FARO data

- Each MPPC position and direction can be described by 6 Parameters.
 - position: x, y, z
 - \triangleright rotation: α , β , γ
- Fitting model (→)
 - > 4 cuboids.
- Data used for fitting:
 - cross at center.
 - side and top part of 4 chips.
- Calculate distance b/w data points and mode
- Find the 6 parameters to minimize sum of (Distance/ σ)².
- Iteration until fitting is converged.
- Apply this process to all 4092 MPPCs

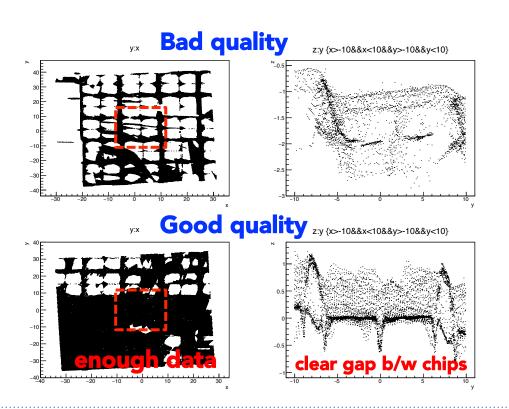


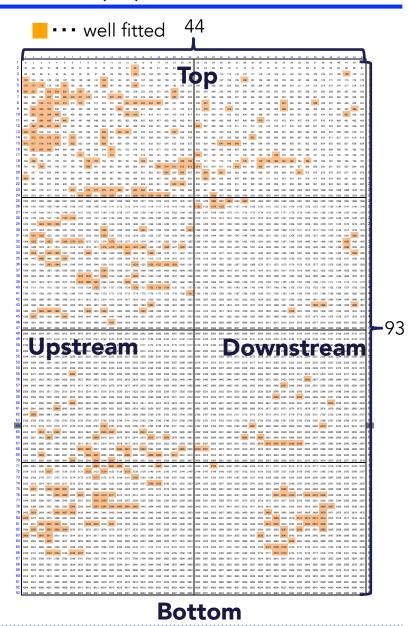


side view of scanned data

Results & Discussion (1)

- Only 356 MPPCs out of 4092 are well fitted and find the position and direction.
- This is due to bad quality of data.
- Data quality depends on reflection and is restricted by accessibility of FARO arm.





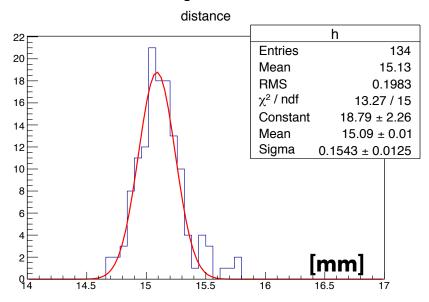
Results & Discussion (2)

Check

- Calculate distance b/w adjacent MPPCs to evaluate fitting accuracy.
- The distance should be 15.1 mm as a design value.
- Mean: 15.09±0.01 mm
- Sigma: 0.15 mm

< 0.5 mm: requirement

Distance b/w adjacent MPPCs calculated only for fitted MPPCs





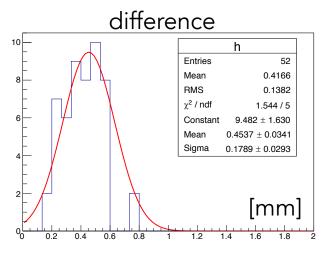
- Good: the accuracy for fitted MPPCs is enough.
- Bad: the number of fitted MPPCs is small.

Solution

- To reconstruct all MPPCs, we tried cylindrical extrapolation.
- 1. divide data points (from FARO fit) into 2 groups
 - one is used for cylindrical fitting(1st datasets).
 - > the other is used for checking(2nd datasets).
- 2. fit with cylinder using 1st datasets and find radius and direction of axis.
- 3. calculate positions of 2nd datasets assuming the fitted cylinder.
- 4. compare calculated position and results from FARO fit.



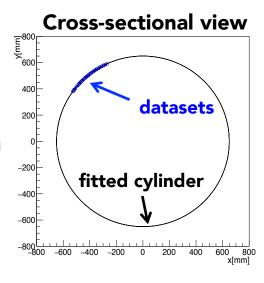
→cylindrical extrapolation seems working well.



Yet another solution:

Picture reconstruction

- 3D reconstruction using pictures from different angles.
- checked consistency and got enough accuracy within ± 2 rows.





same MPPCs from different angles

Prospects

Room temperature

Detector Installation MPPC reconstruction

- Improvement of FARO fitting(by using more MPPCs or better models).
- Cylindrical extrapolation.
- Picture reconstruction.

LXe temperature

2017

Potentiometer

Measure and monitor possible displacement/deformation of inner vessel.



- Produce collimated X-ray beam of known position and orientation.
- > 124/132 keV from ⁵⁷Co
- Spot size at LXe: 1.2 x 40 mm²

2018

Cosmic ray

- In MEG I, cosmic ray were used to measure the position of the DCH frame relative to the LXe detector.
- An accuracy of 1 mm in horizontal and vertical directions were achieved.





Summary

MEG II detector and its alignment

- > 3D scanner and laser tracker are used for measurements of every detector.
- Detectors are aligned to global coordinate.

LXe detector alignment

- ➤ Target accuracy: ~0.5 mm
- In room temperature, MPPCs are measured by 3D scanner and PMT holders are measured by laser tracker.
- In LXe temperature after installation of detector, possible deformation will be measured by x-ray and potentiometer.

MPPC reconstruction using 3D scanned data

- \triangleright Some MPPCs are successfully reconstructed with an accuracy of 0.15 mm.
- Others are failed due to bad quality of data.
- ➤ However, they can be compensated by using cylindrical extrapolation with an accuracy of 0.45 mm.

Prospects

Potentiometer installation and x-ray survey follows towards physics run.